

# FAIRNESS FOR INFINITE STATE SYSTEMS

**Heidy Khlaaf**<sup>1</sup>      Byron Cook<sup>1</sup>      Nir Piterman<sup>2</sup>

University College London<sup>1</sup>  
University of Leicester<sup>2</sup>

# FAIRNESS

- If a process requests a resource infinitely often, then it must be granted infinitely often (resource starvation).
- Verifying fairness:
  - Bridges the gap between trace-based and state-based reasoning, allowing us to prove things like fair-termination.
  - When proving state-based properties, fairness is used to model trace-based assumptions about the environment.

# FAIRNESS

```
1  PPBlockInits();
2  while (i < Pdolen) {
3      DName = PPMakeDeviceName(...);
4      if (!DName) { break; }
5      RtlInitUnicodeString(&deviceName, DName);
6      status = IoCreateDevice(...);
7      if (STATUS_SUCCESS != status) {
8          Pdo[i] = NULL;
9          if (STATUS_OBJECT_NAME_COLLISION == status) {
10             ExFreePool(DName);
11             num++;
12             continue;
13         }
14         break;
15     } else {
16         i++;
17     }
18 }
19 num = 0;
20 PPUnblockInits();
```

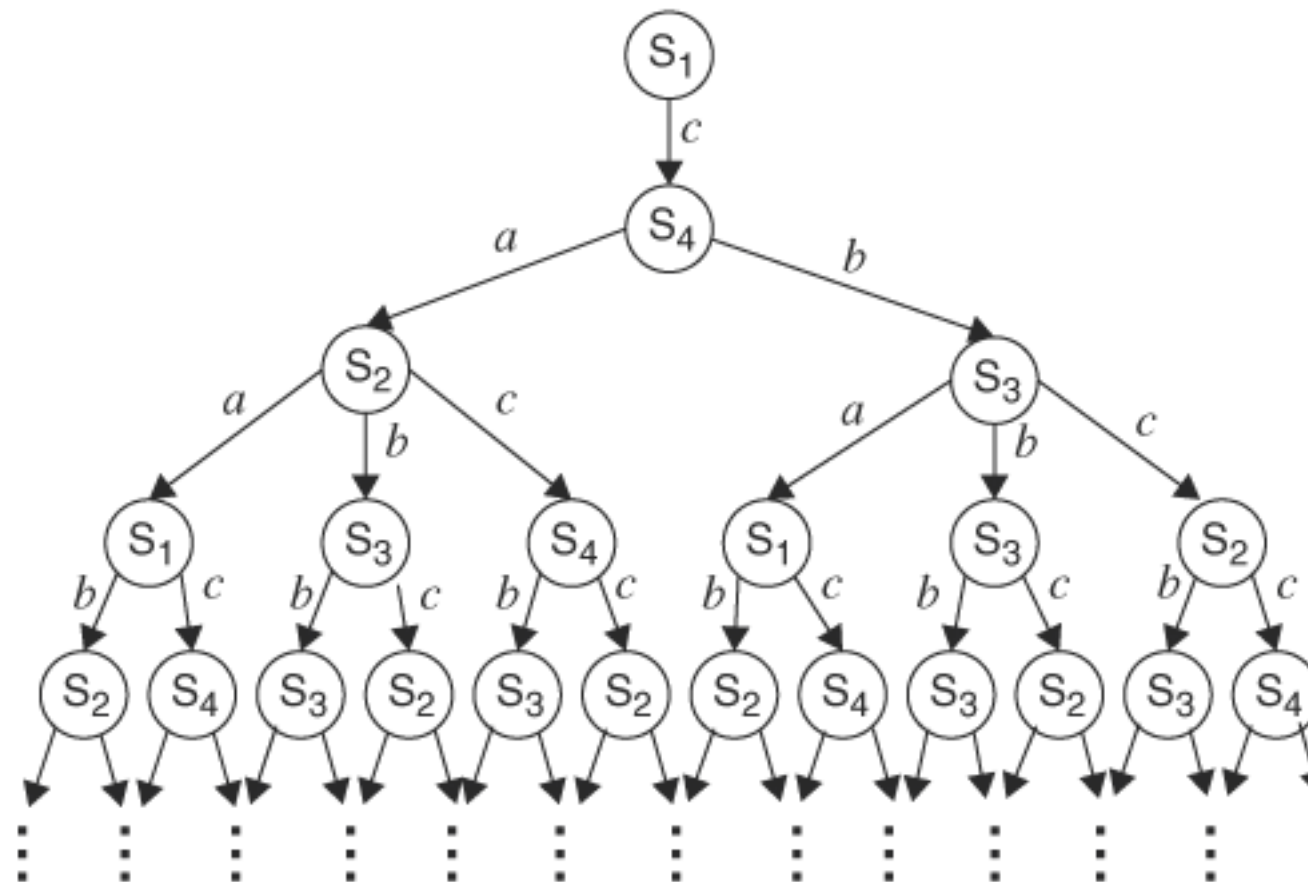
# EMPLOYING FAIRNESS

- First known tool for symbolically proving fair-CTL properties of *infinite*-state programs.
- Solution is based on a reduction to existing techniques for fairness- free CTL model checking via prophecy variables.
- Prophecy variables are auxiliary variables whose values are defined in terms of current program state and future behavior.

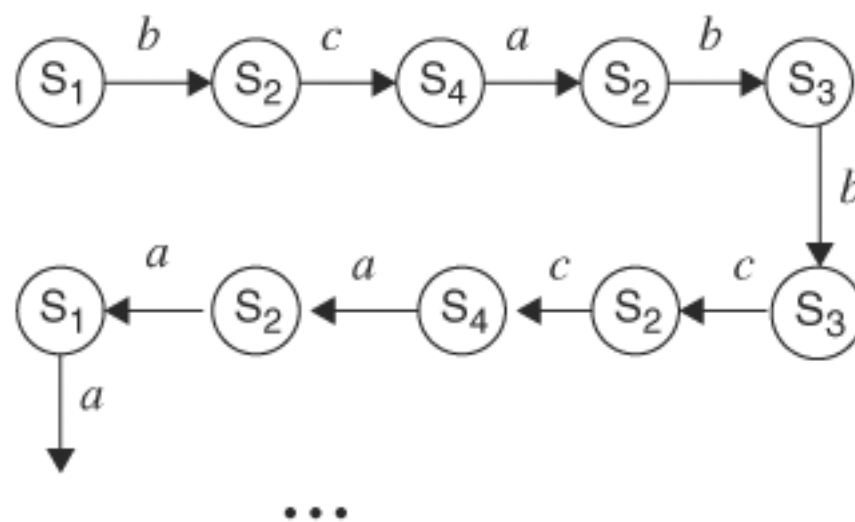
# TEMPORAL LOGIC

- Logic reasoning about propositions qualified in terms of time.
- Used as a specification language as it encompasses safety, liveness, fairness, etc.
- Most commonly used sub-logics are CTL (state based) and LTL (trace based).

# CTL VS LTL



CTL



LTL

# CTL

- Reasoning about sets of states.
- Reasoning about non-deterministic (branching) programs.
- $\varphi ::= \alpha \mid \neg\alpha \mid \varphi \wedge \varphi \mid \varphi \vee \varphi \mid AX\varphi \mid AF\varphi \mid A[\varphi W \varphi] \mid EX\varphi \mid EG\varphi \mid E[\varphi U \varphi]$
- $A \varphi$  – All:  $\varphi$  has to hold on all paths starting from all initial states.
- $E \varphi$  – Exists: there exists at least one path starting from all initial states where  $\varphi$  holds.

# CTL

- $X \varphi$  – Next:  $\varphi$  has to hold at the next state.
- $G \varphi$  – Globally:  $\varphi$  has to hold on the all states along a path.
- $F \varphi$  – Finally:  $\varphi$  eventually has to hold.
- $\varphi_1 U \varphi_2$  – Until:  $\varphi_1$  has to hold at least until at some position  $\varphi_2$  holds.  $\varphi_2$  must be verified in the future.
- $\varphi_1 W \varphi_2$  – Weak until:  $\varphi_1$  has to hold until  $\varphi_2$  holds.



# LTL

- Reasoning about sets of paths.
- Reasoning about concurrent programs.
- $\psi ::= \alpha \mid \psi \wedge \psi \mid \psi \vee \psi \mid G\psi \mid F\psi \mid [\psi W \psi] \mid [\psi U \psi] .$
- Properties expressed in the universal fragment of CTL ( $\forall$ CTL) are easier to prove than LTL properties.

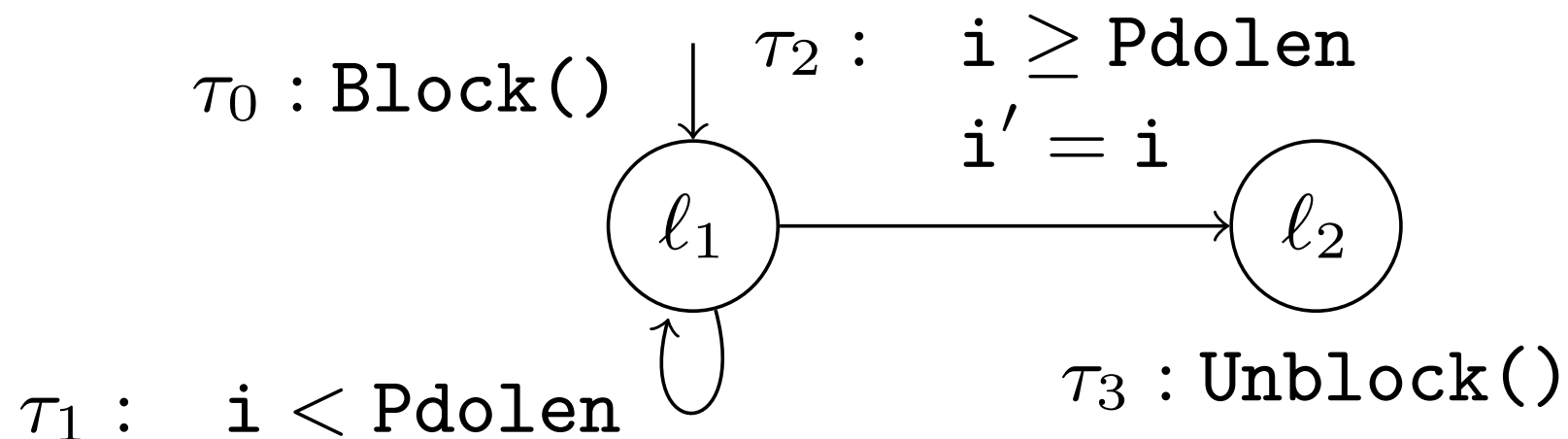
# LTL

- Can naturally express fairness:  $GF\ p \Rightarrow GF\ q$ .
- Path based property not expressible in CTL.
- When proving state-based CTL properties, we must often use fairness to model path-based assumptions about the environment.
- When reasoning about concurrent environments, fairness is used to abstract away the scheduler.

# FAIR LIVENESS $AG (BLOCK() \Rightarrow AF UNBLOCK())$

```
1  PPBlockInits();
2  while (i < Pdolen) {
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4      if (!DName) { break; }
5      RtlInitUnicodeString(&deviceName, DName);
6      status = IoCreateDevice(...);
7      if (STATUS_SUCCESS != status) {
8          Pdo[i] = NULL;
9          if (STATUS_OBJECT_NAME_COLLISION == status) {
10             ExFreePool(DName);
11             num++;
12             continue;
13         }
14         break;
15     } else {
16         i++;
17     }
18 }
19 num = 0;
20 PPUnblockInits();
```

# FAIR LIVENESS



- Transition system contains a non-terminating execution.
- However, if we only allow fair executions, then it is fair-terminating given that there exists no infinite fair paths such that if  $\tau_1$  occurs infinitely often then so does  $\tau_2$ .
- CTL can express liveness properties such as  **$\text{AG}(\text{Block}()) \Rightarrow \text{AF } \text{unblock}()$**  but not that it should hold only under fair paths.

# FAIR CTL

- A transition system  $M = (S, S_0, R, L)$  and a fairness condition  $\Omega = (p, q)$  where  $p, q \subseteq S$ .
- An infinite path  $\pi$  is unfair under  $\Omega$  if states from  $p$  occur infinitely often along  $\pi$  but states from  $q$  occur finitely often. Otherwise,  $\pi$  is fair.

# FAIR CTL

- Fair CTL model checking restricts the checks to only fair paths:
  1.  $M, si \models_{\Omega+} A\varphi$  iff  $\varphi$  holds in ALL fair paths.
  2.  $M, si \models_{\Omega+} E\varphi$  iff  $\varphi$  holds in one or more fair paths.
- Idea: Reduce fair CTL to fairness-free CTL via prophecy variables.
- Use the prophecy to encode a partition of fair from unfair paths.

# THE REDUCTION

$$\text{FAIR}((S, S_0, R, L), (p, q)) \triangleq (S_\Omega, S_\Omega^0, R_\Omega, L_\Omega)$$

where

$$\begin{aligned} S_\Omega &= S \times \mathbb{N} \\ R_\Omega &= \{((s, n), (s', n')) \mid (s, s') \in R\} \wedge \left( \begin{array}{c} (\neg p \wedge n' \leq n) \vee \\ (p \wedge n' < n) \vee \\ q \end{array} \right) \\ S_\Omega^0 &= S^0 \times \mathbb{N} \\ L_\Omega(s, n) &= L(s) \end{aligned}$$

- $n$  is decreased whenever a transition imposing  $p \wedge n' < n$  is taken.
- Since  $n \in \mathbb{N}$ ,  $n$  cannot decrease infinitely often, enforcing the eventual invalidation of the transition  $p \wedge n' < n$ .
- $R_\Omega$  would only allow a transition to proceed if  $q$  holds or  $\neg p \wedge n' \leq n$  holds. That is, either  $q$  occurs infinitely often or  $p$  will occur finitely often.

# TRANSFORMATION

$$R' = R \cup \{(s, s) \mid \forall s'. (s, s') \notin R\} \quad L'(s) = \begin{cases} L(s) \cup \{t\}, & \text{if } \forall s'. (s, s') \notin R \\ L(s), & \text{otherwise} \end{cases}$$

- $Fair(M, \Omega)$  can include finite paths that are prefixes of unfair infinite paths due to the wrong estimation of the number of  $p$ -s until  $q$ .
- Must ensure that these paths do not interfere with the validity of our model checking procedure.
- We distinguish between finite paths that occur in  $M$  and those introduced by our reduction.
- Add a self-loop with proposition  $t$  to mark all original “valid” termination states.

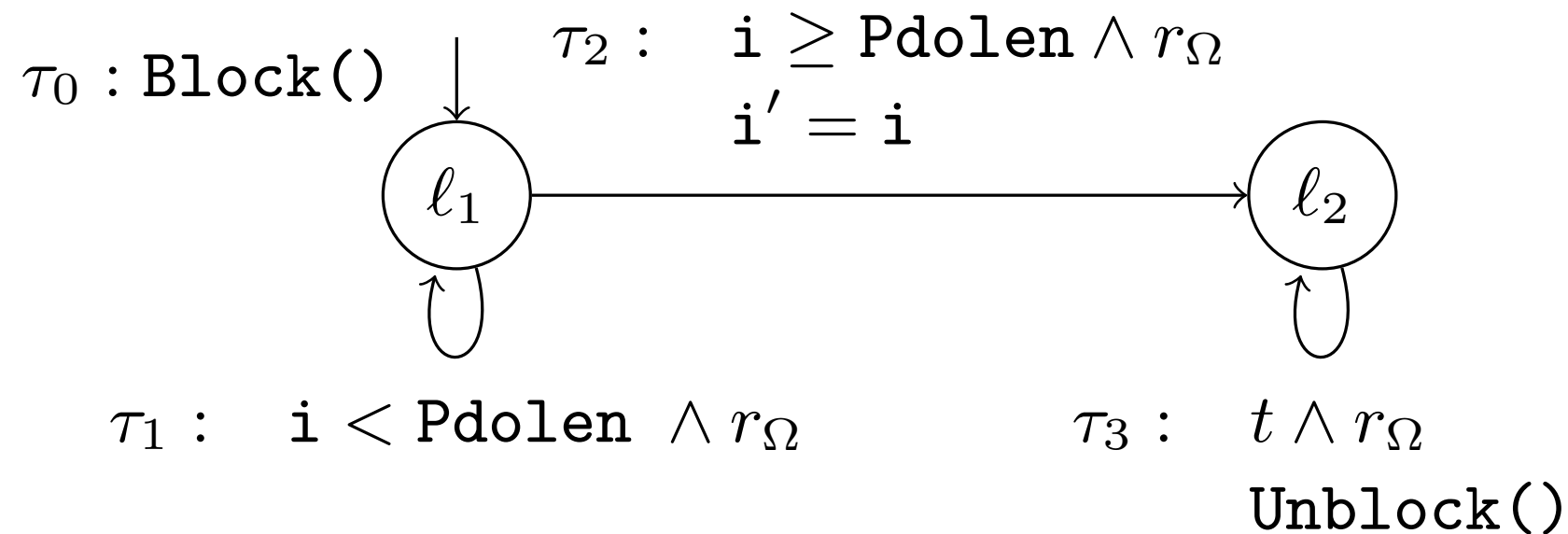


# TRANSFORMATION

$$\begin{aligned}\text{TERM}(\alpha, t) &::= \alpha \\ \text{TERM}(\varphi_1 \wedge \varphi_2, t) &::= \text{TERM}(\varphi_1, t) \wedge \text{TERM}(\varphi_2, t) \\ \text{TERM}(\varphi_1 \vee \varphi_2, t) &::= \text{TERM}(\varphi_1, t) \vee \text{TERM}(\varphi_2, t) \\ \text{TERM}(\mathbf{AX}\varphi, t) &::= t \vee \mathbf{AX}(\text{TERM}(\varphi, t)) \\ \text{TERM}(\mathbf{AF}\varphi, t) &::= \mathbf{AF}\text{TERM}(\varphi, t) \\ \text{TERM}(\mathbf{A}[\varphi_1 \mathbf{W} \varphi_2], t) &::= \mathbf{A}[\text{TERM}(\varphi_1, t) \mathbf{W} \text{TERM}(\varphi_2, t)] \\ \text{TERM}(\mathbf{EX}\varphi, t) &::= \neg t \wedge \mathbf{EX}(\text{TERM}(\varphi, t)) \\ \text{TERM}(\mathbf{EG}\varphi, t) &::= \mathbf{EG}\text{TERM}(\varphi, t) \\ \text{TERM}(\mathbf{E}[\varphi_1 \mathbf{U} \varphi_2], t) &::= \mathbf{E}[\text{TERM}(\varphi_1, t) \mathbf{U} \text{TERM}(\varphi_2, t)]\end{aligned}$$

- Adjust the CTL specification to accommodate for this change.
- $M \models_{\Omega^+} \boldsymbol{\varphi} \Leftrightarrow \text{Term}(M, t) \models_{\Omega^+} \text{Term}(\boldsymbol{\varphi}, t)$

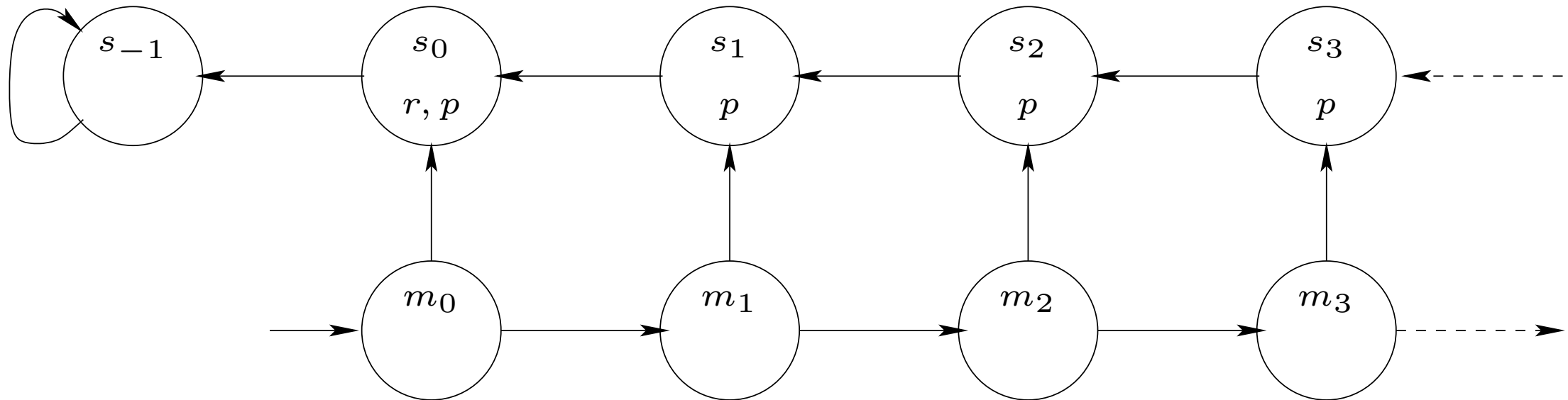
# FAIR TERMINATION - REVISITED



$$r_\Omega : \{ (\neg \tau_1 \wedge n' \leq n) \vee (\tau_1 \wedge n' < n) \vee \tau_2 \} \wedge n \geq 0$$

- CTL property **AG(lock()  $\Rightarrow$  AF unlock())**.
- Strong fairness constraint  $\Omega = (\tau_1, \tau_2)$ .

# ECTL



- $M, m_0 \models_{\Omega^+} \text{EG}(\neg p \wedge \text{EF } r)$  for  $\Omega = (p, q)$ .
- From  $s_i$  there is a path that eventually reaches  $s_0$ , where it satisfies  $r$ , and then continues to  $s_{-1}$ , where  $p$  does not hold.
- The paths which satisfy  $\text{EG}(\neg p \wedge \text{EF } r)$  are fair.
- However, system does not hold under  $\text{Fair}(M, \Omega)$ .

# FAIR CTL

- As long as a new prophecy variable is introduced for each temporal sub-formula, the reduction can still be applied.
- Recurse over each sub-formula, and add a non-termination ( $E\varphi$ ) or termination ( $A\varphi$ ) clause, allowing us to ignore finite paths that are prefixes of unfair infinite-paths.
- Apply our reduction  $\text{Fair}(M, \Omega)$  and run with  $\varphi$  on an existing CTL model checker which returns an assertion  $a$  characterizing the states in which  $\varphi$  holds.
- $E\varphi \rightarrow \exists n \geq 0 . a$
- $A\varphi \rightarrow \forall n \geq 0 . a$

# FAIR CTL

```

1 let FAIRCTL( $M, \Omega, \varphi$ ) : assertion =
2
3   match( $\varphi$ ) with
4   |  $\mathbf{Q} \ \varphi_1 \ \mathbf{OP} \ \varphi_2$ 
5   |  $\varphi_1 \ \mathbf{bool\_OP} \ \varphi_2 \rightarrow$ 
6        $a_{\varphi_1} = \text{FAIRCTL}(M, \Omega, \varphi_1);$ 
7        $a_{\varphi_2} = \text{FAIRCTL}(M, \Omega, \varphi_2)$ 
8   |  $\mathbf{Q} \ \mathbf{OP} \ \varphi_1 \rightarrow$ 
9        $a_{\varphi_1} = \text{FAIRCTL}(M, \Omega, \varphi_1)$ 
10  |  $\alpha \rightarrow$ 
11       $a_{\varphi_1} = \alpha$ 
12
13  match( $\varphi$ ) with
14  |  $\mathbf{E} \ \varphi_1 \ \mathbf{U} \ \varphi_2 \rightarrow$ 
15       $\varphi' = E[a_{\varphi_1} \ \mathbf{U} \ (a_{\varphi_2} \wedge \neg \text{term})]$ 
16  |  $\mathbf{E} \ G\varphi_1 \rightarrow$ 
17       $\varphi' = EG(a_{\varphi_1} \wedge \neg \text{term})$ 
18  |  $\mathbf{E} \ X\varphi_1 \rightarrow$ 
19       $\varphi' = EX(a_{\varphi_1} \wedge \neg \text{term})$ 
20  |  $\mathbf{A} \ \varphi_1 \ \mathbf{W} \ \varphi_2 \rightarrow$ 
21       $\varphi' = A[a_{\varphi_1} \ \mathbf{W} \ (a_{\varphi_2} \vee \text{term})]$ 
22
23  |  $\mathbf{A} \ F\varphi_1 \rightarrow$ 
24       $\varphi' = AF(a_{\varphi_1} \vee \text{term})$ 
25  |  $\mathbf{A} \ X\varphi_1 \rightarrow$ 
26       $\varphi' = AX(a_{\varphi_1} \vee \text{term})$ 
27  |  $\varphi_1 \ \mathbf{bool\_OP} \ \varphi_2 \rightarrow$ 
28       $\varphi' = a_{\varphi_1} \ \mathbf{bool\_OP} \ a_{\varphi_2}$ 
29  |  $\alpha \rightarrow$ 
30       $\varphi' = a_{\varphi_1}$ 
31
32   $M' = \text{FAIR}(M, \Omega)$ 
33   $a = \text{CTL}(M', \varphi')$ 
34
35  match( $\varphi$ ) with
36  |  $\mathbf{E} \ \varphi' \rightarrow$ 
37      return  $\exists n \geq 0 . a$ 
38  |  $\mathbf{A} \ \varphi' \rightarrow$ 
39      return  $\forall n \geq 0 . a$ 
40  |  $- \rightarrow$ 
41      return  $a$ 

```

- $\text{FairCTL}(M, \Omega, \varphi)$  employs an existing CTL model checker and the reduction  $\text{Fair}(M, \Omega)$ . An assertion characterizing the states in which  $\varphi$  holds under the fairness constraint  $\Omega$  is returned.

# EXPERIMENTS

Program	LOC	Property	FC	Time(s)	Result
WDD1	20	$AG(\text{BlockInits}() \Rightarrow AF \text{ UnblockInits}())$	Yes	14.4	✓
WDD1	20	$AG(\text{BlockInits}() \Rightarrow AF \text{ UnblockInits}())$	No	2.1	✗
WDD2	374	$AG(\text{AcqSpinLock}() \Rightarrow AF \text{ RelSpinLock}())$	Yes	18.8	✓
WDD2	374	$AG(\text{AcqSpinLock}() \Rightarrow AF \text{ RelSpinLock}())$	No	14.1	✗
WDD3	58	$AF(\text{EnCritRegion}() \Rightarrow EG \text{ ExCritRegion}())$	Yes	12.5	✗
WDD3	58	$AF(\text{EnCritRegion}() \Rightarrow EG \text{ ExCritRegion}())$	No	9.6	✓
WDD4	302	$AG(\text{added\_socket} > 0 \Rightarrow AFEG \text{ STATUS\_OK})$	Yes	30.2	✓
WDD4	302	$AG(\text{added\_socket} > 0 \Rightarrow AFEG \text{ STATUS\_OK})$	No	72.4	✗
Bakery	37	$AG(\text{Noncritical} \Rightarrow AF \text{ Critical})$	Yes	2.9	✓
Bakery	37	$AG(\text{Noncritical} \Rightarrow AF \text{ Critical})$	No	16.4	✗
Prod-Cons	30	$AG(p_i > 0 \Rightarrow AF q_i \leq 0)$	Yes	18.5	✓
Prod-Cons	30	$AG(p_i > 0 \Rightarrow AF q_i \leq 0)$	No	5.5	✗
Chain	48	$AG(x \geq 8 \Rightarrow AF x = 0)$	Yes	1.8	✓
Chain	48	$AG(x \geq 8 \Rightarrow AF x = 0)$	No	4.7	✗

# RECAP

- Introduced the first known method for symbolically proving fair-CTL properties of (infinite-state) integer programs.
- Solution is based on a reduction which allows the use and integrate with any off-the-shelf CTL tool
- Use prophecy variables in the reduction for the purpose of symbolically partitioning fair from unfair executions.
- Implemented as an extension to **T2**, a CTL model checker which returns assertions characterizing the states in which a property holds.